

# **Vibrating Transmission (Acoustics)**





#### Copyright © 2020 FunctionBay, Inc. All rights reserved.

User and training documentation from FunctionBay, Inc. is subjected to the copyright laws of the Republic of Korea and other countries and is provided under a license agreement that restricts copying, disclosure, and use of such documentation. FunctionBay, Inc. hereby grants to the licensed user the right to make copies in printed form of this documentation if provided on software media, but only for internal/personal use and in accordance with the license agreement under which the applicable software is licensed. Any copy made shall include the FunctionBay, Inc. copyright notice and any other proprietary notice provided by FunctionBay, Inc. This documentation may not be disclosed, transferred, modified, or reduced to any form, including electronic media, or transmitted or made publicly available by any means without the prior written consent of FunctionBay, Inc. and no authorization is granted to make copies for such purpose.

Information described herein is furnished for general information only, is subjected to change without notice, and should not be construed as a warranty or commitment by FunctionBay, Inc. FunctionBay, Inc. assumes no responsibility or liability for any errors or inaccuracies that may appear in this document.

The software described in this document is provided under written license agreement, contains valuable trade secrets and proprietary information, and is protected by the copyright laws of the Republic of Korea and other countries. UNAUTHORIZED USE OF SOFTWARE OR ITS DOCUMENTATION CAN RESULT IN CIVIL DAMAGES AND CRIMINAL PROSECUTION.

#### Registered Trademarks of FunctionBay, Inc. or Subsidiary

RecurDyn is a registered trademark of FunctionBay, Inc.

RecurDyn/Professional, RecurDyn/ProcessNet, RecurDyn/Acoustics, RecurDyn/AutoDesign, RecurDyn/Bearing, RecurDyn/Belt, RecurDyn/Chain, RecurDyn/CoLink, RecurDyn/Control, RecurDyn/Crank, RecurDyn/Durability, RecurDyn/EHD, RecurDyn/Engine, RecurDyn/eTemplate, RecurDyn/FFlex, RecurDyn/Gear, RecurDyn/DriveTrain, RecurDyn/HAT, RecurDyn/Linear, RecurDyn/Mesher, RecurDyn/MTT2D, RecurDyn/MTT3D, RecurDyn/Particleworks I/F, RecurDyn/Piston, RecurDyn/R2R2D, RecurDyn/RFlex, RecurDyn/RFlexGen, RecurDyn/SPI, RecurDyn/Spring, RecurDyn/TimingChain, RecurDyn/Tire, RecurDyn/Track\_HM, RecurDyn/Track\_LM, RecurDyn/TSG, RecurDyn/Valve

are trademarks of FunctionBay, Inc.

#### **Edition Note**

This document describes the release information of **RecurDyn V9R4**.

# Contents

Overview	4
Task Objectives	4
Prerequisites	5
Task	5
Estimated Time to Complete this Task	5
Simulating and analyzing the initial model	6
Task Objectives	6
Estimated Time to Complete This Task	6
Opening the Model	7
Performing Simulation	9
Changing an existing body to the RFlex body1	0
Task Objectives1	.0
Estimated Time to Complete This Task 1	.0
Modifying a Model Using a RFlex Body1	.1
Redefining Contact 1	.3
Performing Simulation1	.8
Calculating Equivalent Radiated Power2	1
Task Objectives	21
Estimated Time to Complete This Task 2	21
Viewing Acoustics Result 2	22
Viewing Acoustics Results for Modal ERP 2	26
Modifying and Analyzing the Model3	1
Task Objectives	31
Estimated Time to Complete This Task	31
Replacing the Housing	32
Viewing the Acoustics Result	33



# **Overview**

As the quality of human life improves, many efforts are being made to control noise and vibration in various industries. In the mechanical industry, it is very important to find out the part that generates a large amount of vibration and the frequency band with a large amplitude.

The example model used in this tutorial is a link system that makes rotary motion into the reciprocating motion with a vibrating transmission. When analyzing the vibration generated in the housing of this mechanical system, it is difficult to analyze clearly where and what kind of vibration occurs from the result of the existing FE analysis alone.

Therefore, this tutorial introduces and explains a method to calculate the ERP (equivalent radiated power) generated in the housing by using the post tool called Acoustics, which analyzes the noise vibration, and a method of analyzing the vibration occurring in the housing using the post functions.

# **Task Objectives**

This tutorial covers the following topics:

- How to replace RFlex Body through RecurDyn/RFLEX
- How to perform ERP calculation and analysis through RecurDyn/Acoustics

# **Prerequisites**

This tutorial is intended for users who have completed the Basic and FFlex/RFlex tutorials provided with RecurDyn. If you have not completed these tutorials, then you should complete them before proceeding with this tutorial. In addition, this tutorial requires a basic understanding of dynamics and the finite element method.

# Task

The following table outlines the tasks involved in this tutorial and their duration.

Procedures	Time (minutes)
Simulating and analyzing the initial model	5
Changing an existing body to the RFlex body	15
Calculating equivalent radiated power	15
Modifying and analyzing the model	15
Total	50



75 minutes



# Simulating and analyzing the initial model

# **Task Objectives**

Open the initial model, perform a simulation, and observe the behavior of the vibrating transmission.

# Estimated Time to Complete This Task

5 minutes

# **Opening the Model**

#### To copy the example model:

- Copy the Acoustics tutorial example folder provided by RecurDyn to an analyzable location.
- Folder path: <Install Dir>\Help\Tutorial\PostAnalysis\Acoustics\VibratingTransmission

#### To run RecurDyn and open the initial model:

- RecurDyn
- 1. On the Desktop, double-click the **RecurDyn** icon to run **RecurDyn**. The **Start RecurDyn** dialog window will appear.
- 2. When the **Start RecurDyn** dialog window appears, close it.
- 3. In the File menu, click Open.
- 4. In the Acoustics folder copied above, select **VibratingTransmission\_Start.rdyn**.
- 5. Click **Open**. The model appears as shown in the following figure.



#### To analyze the model:

- 1. Click Layer Settings in the Render Toolbar.
  - 2. In the Layer Settings dialog window, turn **on** and off each layer to analyze the model.

The following explains the configuration of the model.



The Model generally consists of 5 parts: **Housing**, **Bearing**, **Shaft**, **Link**, and **Mass**. When the rotary motion is delivered from the lower drive shaft, the pendulum on the upper shaft performs the periodic motion through the link system.

The connection between the shaft, bearing and link are all made up of bushing force, and the housing and bearing are composed of **GeoSurContact**.

The drive shaft is driven by **CMotionGroup** and rotates at 100 \* 2PI per second.

## **Performing Simulation**

Run the simulation to help you understand the model system.

#### To run the simulation:



1. On the Analysis tab, in the Simulation Type group, click the Dyn/Kin icon.

The Dynamic/Kinematic Analysis dialog window appears.

- 2. After verifying the simulation conditions, click **Simulation**.
  - End Time: 0.1
  - Step: 500

#### To view the result:

 Under the Analysis tab, in the Animation Control group, press the Play button to check if the system operates as shown in the figure below.

As described in the "Analyzing the model" section, the motion delivered from the lower drive shaft is transmitted to the link system, and finally the mass on the upper shaft makes a periodic motion.

In the process of power transmission as shown in the figure, the housing receives contact force from 4 bearings.

If you observe the force display of the contact force, you can notice that it moves at a certain cycle. To analyze how this external force directly affects the housing, it is necessary to change the housing, which is a rigid body, to a flexible body.





# Changing an existing body to the RFlex body

Since the housing of the RecurDyn model is a rigid body, you cannot see the deformation of the body due to external force. Therefore, we will perform the RFlex Body Swap function provided by RecurDyn to replace the housing with a flexible body. In addition, the Acoustics Post Tool to be performed in the later chapter can only be performed on a flexible body.

# **Task Objectives**

In this chapter, you will learn how to change an existing rigid body to a flexible body using the RFlex Body Swap function provided by RecurDyn/RFlex.



15 minutes

## Modifying a Model Using a RFlex Body

#### To swap with a RFlex Body:



- 1. On the Flexible tab, in the RFlex group, select Import RFI.
- 2. Change the modeling option to **Body**.

Point	×
Point	
Body	
Group	

3. In the working window, select the **housing** using the mouse as shown below. The RFlex Body Import dialog window appears.



- 4. In the RFlex Body Import dialog window, perform the following:
  - a. Press ... button in the **RFI File Name** field.
  - b. Select the **Housing.rfi** file located in the Acoustics folder copied in Chapter 2.
- 5. Verify that the selected conditions match those shown in the figure to the right, and then click **OK**.

You can verify that the **housing** was replaced by a **RFlex body**.

RFlex Body Impor	t			
RecurDyn RFlex F	RecurDyn RFlex File			
RFI File Name	D:\AcousticsTutorial\Housing.rfi			
Body(Swapped)	Housing			
Reference	Housing			
OK Cancel Options				

The swapped housing looks like a wire frame. Change each rendering just like the previous **housing**.

#### To change each rendering:

- 1. In working window, select the **housing** that changed to a RFlex body.
- 2. Right-click the working window.
- 3. In the pop-up menu, change Each Rendering to **Shade with Wire**.



## **Redefining Contact**

When changing from a rigid body to a RFlex body, the information about contact patches will disappear and all existing GeoSurContact will also disappear. After creating the patches again in the housing, you need to redefine the contact.

#### **To create PatchSet:**

- 1. Enter the **Edit Mode** of the RFlex body.
- 2. Change the plane to the **YZ** plane.
- 3. In Select Toolbar, click Element.
- 4. In the working window, select a half of the housing.

#### **5.** In **Select Toolbar**, click **Set Masking**.

Only the selected part of the housing will be masked as shown below. Now you can easily select the inside of the housing.





6. In the Set group of the FRFlex Edit tab, click Patch Set [ Current Unit : N/kg/mm/s/deg ]
General External Patch Set

Patch

7. Click **Add/Remove (Continuous)** in the Patch Set dialog window.

raten bet [ carrent e	Since ( A) (a) (a) (a) (a) (a) (a) (a) (a) (a) (a	
General External Pat	tch Set	_
Color	Automatic	
Add/Remo	ove	
Add/Remove (Cor	ntinuous) Tolerance (Degree) 45	
	Check Reverse Direction	
Add/Remove (Sel	ect Front)	
Add (Node	Set)	
Preview Normal		
Normal Adjust —		
Automatic	Auto Adjust Switch	
Manual	Select Target Switch	
No. of Patches	0	
	OK Cancel	

- 8. Select the upper bearing position as shown on the right.
- 9. Right-click the working window and click **Finish Operation** in the pop-up menu.
- 10. Click **OK** in the Patch Set dialog window.
- 11. Repeat steps **3 to 10** to create a patch set in other bearing positions as shown below.







## 12. In Select Toolbar, click Set Reverse Masking.

Only except for the selected part above will be masked as shown right.



13. Repeat steps **3 to 10** to create a patch set in other bearing positions as shown to the right.



- 14. When the four patch sets are created, click **Cancel Masking** on the **Select Toolbar**.
- Kit



Define the contact between the patch set and the bearing.

#### To create Geo Surface Contact:



- 1. On the **Flexible** tab, in the **RFlex** group, click **GeoSur**.
- 2. Change the Creation Method to Surface(PatchSet), Surface(PatchSet).
- 3. Click Layer Settings in the Render Toolbar.
- 4. In the Layer Settings dialog window, check **On** only for the **UpperBearing**.
- 5. In the working window, click **UpperBearing1.ImportedSolid1.Face3**.



- 6. In the Layer Settings dialog window, turn off **UpperBearing** and ensure that only the **housing** is visible.
- 7. Click the patch set of the **housing** suitable for the position of bearing selected in **5**.



#### GeoSurContact1 is created.

8. Repeat steps **1 to 7** to create a contact in the remaining bearing positions.

Modify the Contact property to the same state as in the initial model.

#### Modifying the property of GeoSurContact

- In the Database panel, select GeoSurContact1, GeoSurContact2, GeoSurContact3, and GeoSurContact4 and open the Multi Property dialog window.
- 2. Turn off the **Edge Contact** option.
- 3. Set the Force Display as Action.

4 entities [ Current Unit : N/kg/mm/s/deg ] General Characteristic Geo Contact — Definition of the Base Geometry— Gr Name Normal Direction 💿 Up 🔷 Down 🗌 Node Contact Calculate Pressure Preview Contact Geometry Definition of the Action Geometry -Gr Name Geometry Type Surface -Normal Direction 🖲 Up 🔷 Down 🗹 Node Contact Calculate Pressure Preview Contact Geometry Edge Contact Advanced Setting No. of Max Contact Points 10 ÷ Generate the contact output file. (\*.con) Ground.InertiaMarker Action Force Display ÷ ОК Cancel Apply

- 4. Click Advanced Setting.
- 5. In the Advanced Setting dialog window, turn on **Smooth Node Contact** and press **OK**.

Advanced Setting	×
Smooth Option Control —	
CPM Control	
[	OK Cancel

- 6. Move to the **Characteristic** tab on the Multi Property dialog window.
- 7. Modify Stiffness Coefficient to 1000000.
- 8. Modify **Damping Coefficient** to **100**.

Tupo Standard Cantart F		
Characteristic	bre	•
Stiffness Coefficient	1000000.	Pv
Damping Coefficient 🔻	100.	Pv
Dynamic Friction Coefficient 🔻	0. Pv Fri	ction
Stiffness Exponent	2.	Pv
Indentation Exponent	Boundary Penetration	
Boundary Penetration	1.e-002	Pv
Rebound Damping Factor	0.25	Pv
Maximum Penetration	1.	Pv
Maximum Stepsize Factor	10.	Pv
0	K Cancel	Apply

Save As

#### To save the model:

Save the model as VibratingTransmission\_RFlex.rdyn.

17

# **Performing Simulation**

Run simulation to see if the model has been properly converted to a RFlex body.

#### To run the simulation:



1. On the Analysis tab, in the Simulation Type group, click the Dyn/Kin icon.

The **Dynamic/Kinematic Analysis** dialog window appears.

- 2. Confirm the settings.
- 3. On the **General** page, set as follows:
  - End Time: 0.1
  - **Step**: 500

Dynamic/K	inematic Analysis		x		
General Parameter Initial Condition					
End Tim	e	0.1	Pv		
Step		500.	Pv		
Plot Mu	ltiplier Step Factor	1.	Pv		
Outp	out File Name				

#### 4. On the **Parameter** page, enable the option **Match Solving Stepsize with Report Step**.

In the next chapter, when calculating the FFT of the ERP, the data is divided at an equal interval. So you can use this option to produce better results.

5. Click the **Simulate** button.

Dynamic/Kinematic Analysis		×
General Parameter Initial Cond	lition	
Maximum Time Step	1.e-002	Pv
Initial Time Step	1.e-004	Pv
Error Tolerance	5.e-003	Pv
Integrator Type	IMGALPHA	•
Numerical Damping	1.	Pv
Constant Stepsize	1.e-005	
Jacobian Evaluation for TPart	1.	
Match Solving Stepsize with R	leport Step	
Match Simulation End Time w	ith User Input	
Stop Condition		
Export RSS Simo	ulate OK Ca	ncel

#### To view the stress contour result:



- 1. On the **Flexible** tab, in the **RFlex** group, click **Contour**.
- 2. In Contour Option, set the **Type** to **Stress**.
- 3. In Contour Option, set the **Component** to **SMISES**.
- 4. In Min/Max Option, set the **Type** to **User Defined**.
- 5. Click the **Calculation** button.
- 6. Change Max to **10**.
- 7. Select the **Show Min/Max** checkbox.
- 8. Click **OK**.

Contour Option —			Band Option			View /	Reference No	de
Animation Status	SMISES		Legend Type	Display	-	Sel	Body	Node ID Sel
Туре	Stress	•	Location	Bottom	•		Housing	1 <u>N</u>
Component	SMISES	•		Show Text Legend	d			
Display Vector	14.61751707011	114	Band Level(10~50)		10			
Uniform	Simple		Style Option			- Contor	ur Data Traca	
Contact Surface	Only		Color Option	Edit		Sel	Body	Node ID
User define	ed contact surface		Colors	Spectrum	<b>•</b>		500,	
🔘 Contact pa	tches only		Style	Stepped	<b>_</b>			
Min/Max Option —			Text Color	Text Color	•			
SMISES							Add	Delete
Type User Defined		•	Exceed Max Color	Max Color	· ·			
0	alculation					Conto	Body Body	Selection
Calc. Result	User Define	ed					body	contourrait
Min		0						
Max 29.35	508	10						
Show Min/Max	Enable Log S	cale						
		- and			_			
User Defined Ma	x Color		Mesh Lines	Line Color	•		Add	Delete
Enable Contour	View							

#### To view animation:

►

 On the Analysis tab, in the Animation Control group, click the Play button to check the result of stress. At 0.0548 seconds, you can see that the result of Maximum Von-Mises Stress is approximately 20 Mpa.





# Calculating Equivalent Radiated Power

The Acoustics analysis is a post tool and can be performed at any time with the analysis result of a flexible body (FFlex, RFlex). In the case of RFlex body, ERP can be additionally calculated for each mode, so you can analyze which mode affects it the most.

# **Task Objectives**

In this chapter, you will learn how to calculate the ERP (equivalent radiated power) results using the functions provided by RecurDyn / Acoustics, and to derive the results through Scope and Contour.



15 minutes

## **Viewing Acoustics Result**

Acoustics analysis is carried out using the result simulated in Chapter 3. Before proceeding with the analysis, you should set the range for calculating ERP using a patch set.

#### What is ERP (equivalent radiated power)?

One of the methods to analyze the frequency response of surface vibrations in a flexible body is to analyze the ERP results.

ERP is the sum of vibration energy generated from the surface as shown in the following equation.

$$\text{ERP} = \text{RLF} * \left(\frac{1}{2}\right) * \text{C} * \text{RHO} * \sum \left(A_i * V_i^2\right)$$

RLF: Radiation Loss Factor C: Sound Velocity RHO: Air Density  $A_i$ : Surface Area of Each Element  $V_i$ : Normal Velocity of Each Element.



**RecurDyn** calculates the ERP by calculating the area and vertical velocity of each element for a specific patch set defined by the user. The ERP results for time domain and the results of using FFT (Fast Fourier Transform) as frequency domain are provided through Acoustic Scope. You can also check the ERP results using Contour animation.

#### To create a patch set for Acoustics calculation:

- 1. Enter the RFlex Edit mode of the **Housing**.
- 2. In the **Set** group of the F**RFlex Edit** tab, click **Patch**.
- 3. In Tolerance (Degree), enter 1.
- 4. Click **Add/Remove (Continuous)** in the Patch Set dialog window.

5. Click the side of the **housing** as shown on the right.

The entire side is selected.

- 6. Right-click the working window and click **Finish Operation** in the pop-up menu.
- Click **OK** in the Patch Set dialog window. SetPatch5 is created.



Exit



#### To reload an animation:

In the process of creating the patch set, the relationship between the model and the animation is lost. Click **Reload the Last Animation file** button to retrieve the animation data to the model again.

(If the reload is not possible, import the RAD or RAN file directly from the analysis result folder.)

#### **To calculate Acoustics:**

Calculation

1. On the **Post Analysis** tab, in the **Acoustics** group, click **Calculation**.

The Calculation dialog window appears.

Since the simulation was performed at 500 steps per 0.1 second, you can extract the 5000 Hz result.

- Modify Sampling Frequency to 5000.
   Sampling frequency is used in the process of performing FFT for ERP.
- 3. In order to add a patch set, click the **Add/Remove** button.
- 4. In the working window, select **Housing.SetPatch5** created right before.
- 5. Right-click the working window and click **Finish Operation** in the pop-up menu.
- 6. Set the **Start Frame** to **1** and **End Frame** to **501**, which is the endmost value.
- 7. Set **Base Name** as **Acoustics**.
- 8. Click the **Calculation** button.
- 9. When the calculations are complete, click **OK** to close the dialog window.

Calculation					
Calculation					
Radiation Los	s Factor (RLF)	1.	Pv		
Sound Veloci	ty (C)	340000.	Pv		
Air Density (R	HO)	1.293e-009	Pv		
Sampling Fre	quency	5000.	Pv		
Patch Set -					
No	Name		Modal ERP		
1	Housing.SetPat	ch5 P	Mode		
Add/Rem	ove	Add Row	Delete Row		
Simulation	lime	Time	Frame		
Start Frame	0	- 0	1		
End Frame		0.1	501		
Result					
			OK Cancel		

#### **To view Acoustics scope:**

- 1. On the **Post Analysis** tab, in the **Acoustics** group, click **Scope**.
- 2. Change the View Type to **ERP-Time Domain**.

Scope shows the ERP calculation result of time domain for the whole housing.

There is a section that is not related to the periodic motion in the stabilizing phase between 0 and 0.005 seconds. In order to proceed with the FFT clearly, the ERP must be calculated again after removing the corresponding interval.

3. Click **Cancel** to close the Acoustics Scope dialog window.





## **Viewing Acoustics Results for Modal ERP**

We will calculate the ERP for each mode of a RFlex body and analyze which mode has the greatest effect on the total ERP.

# To recalculate Acoustics considering the modal ERP:



1. On the **Post Analysis** tab, in **Acoustics** group, click **Calculation**.

The Calculation dialog window appears.

2. Click the **Mode** button of the Housing.**SetPatch5** previously selected.

Calculation			
Calculation			
Radiation Loss Factor	(RLF)	1.	Pv
Sound Velocity (C)		340000.	Pv
Air Density (RHO)		1.293e-009	Pv
Sampling Frequency		5000.	Pv
Patch Set			
No	Name		Modal ERP
1	Housing.SetPat	ch5 P	Mode
Add/Remove		Add Row	Delete Row

The Mode Selection dialog window appears.

3. Select the **Mode** numbers **7**, **8**, and **9** and click **Close**.

Sel.	Sel. Mode ID		Freq.[Hz]					
<b>I</b>	7			3235.5	77577	78405	1	=
	8	8		4023.82261098903				
	9		4136.79204337239					
	10	10		4412.66002630668				
	11		5292.17601547663					
	12		5689.42894733896					
	13 14		6090.6526149146 6346.07160141344					
Ē.	15		6366 73700057382					
•								
Selecti	ion ——							
Mode	Range	7		~	44			
			Select			UnS	elect	
						Sele	ct All	

- 4. Set **Start Frame** to **26** to calculate starting from **0.005 second** to eliminate the interval that seems not related to the periodic motion between 0 second and 0.005 second.
- 5. Change Base Name to Acoustics\_Start0p005.
- 6. Click the **Calculation** button.
- 7. When the calculations are complete, click **OK** to close the dialog window.

		Time	Frame
Start Frame	-]	0.005	26 🗘
End Frame	0	0.1	501 🗘
Result			
Base Directory	InWorkSpece, SPACED un	eradelindonin	ad Analysis (Aspecti
Base Name	Acoustics_Start0p005		
		Import	Calculation

#### To view Acoustics scope:

Scope

- 1. On the **Post Analysis** tab, in the **Acoustics** group, click **Scope**.
- 2. Change the View Type to **ERP-Time Domain**.

Acoustics Scope		
Acoustics Scope		
Patch Set	Housing.SetPatch5	•
Mode	Total	-
View Type	ERP - Time Domain	•
🖻 🖻 🖄 🖾 🐼 🗮	Ф ⊕ 🚰 🚰 🖽 🗉 🚿 🏁 💆	
E 9.60 0.00 4.80 0.00 0.00 0.000 0.010 0.020 0.030	0.040 0.050 0.060 0.070 0.080 0.090 0.100 Time	
L	OK Can	cel

Time Domain ERP calculations are removed for up to 0.005 second, so they are well organized into the analytical data.

Acoustics Scope Acoustics Scope Housing.SetPatch5 ٠ Patch Set Mode Total • ERP - Magnitude • View Type 🖻 🖻 🖄 🔍 🂐 🤁 🖬 🗘 🕀 🎒 隊 🔝 🛅 🕷 6.00 4.80 - Wagnitude 3.60 - 2.40 2.40 1.20 ٨٨ 0.00 250.00500.00750.001000.0250.00500.00750.002000.00250.00500.00 Frequency ОК Cancel

3. Change the View Type to **ERP-Magnitude**.

It can be seen that the harmonic frequency occurs for the 100Hz frequency.



4. Change the mode to analyze the results for **Total**, **Mode7**, **Mode8**, and **Mode9**.

If **ERP-Magnitude** is plotted against **Total**, **Mode7**, **Mode8**, and **Mode9** at once, you can see that Mode7 has the greatest effect.

5. Click **Cancel** to close the Acoustics Scope dialog window.

#### To view the Acoustics Contour result:



- 1. On the **Post Analysis** tab, in the **Acoustics** group, click **Contour**.
- 2. Set the Type to **Acoustics ERP**.
- 3. Set the Component to **ERP**.
- 4. In Min/Max Option, set the Type to **User Defined**.
- 5. Click the **Calculation** button.
- 6. Set Max to **0.01**.
- 7. Select the **Show Min/Max** checkbox.
- 8. Click **OK**.

Contour		×
Contour Option	Band Option	View / Reference Node / Reference Marker
Animation Status ERP	Legend Type Dis	splay 💌 Sel Body Node ID Sel Ori.
Type Acoustics ERP 💌	Location Bot	ttom
Component ERP 💌		Show Text Legend
Display Vector 14.6175170701114	Band Level(10~50)	10
Uniform Simple	Style Option	
Contact Surface Only	Color Option	Edit Contour Data Trace
User defined contact surface     Contact patches only	Colors Spe	ectrum
	Style Ste	epped 💌
Min/Max Option	Text Color	Text Color -
Type User Defined	Exceed Max Color	Max Color 👻
Calculation	Less than Min Color	Min Color + Add Delete
Calc. Result User Defined		Contour Element Set Selection
Min 0 0		Sel Body Contour Part
Max 0.031511 0.01		
Show Min/Max 🗌 Enable Log Scale		
User Defined Max Color		
User Defined Min Color	Mesh Lines	Line Color   Add Delete
Enable Contour View	<u> </u>	
Export		OK Cancel Apply

9. On the Analysis tab, in the Animation Control group, click the Play button to check the result of ERP. The Contour result shows that the ERP value is biggest in the middle part.



10. Again, open the Contour dialog window and draw an ERP Contour for **other Modes**.



The ERP\_HOUSING\_MODE7 result is similar to the Total result, and the rest of the modes is considered to have no significant impact.



# Modifying and Analyzing the Model

# **Task Objectives**

We will try to improve the model so that the noise vibration generated in the housing can be reduced.



15 minutes

# **Replacing the Housing**

#### To replace with a RFlex body:

Repeat the procedure for swapping with the RFlex body that you carried out in **Chapter 3**. For the RFlex body to replace the housing, use the file **Housing\_Modified.rfi** in the folder copied in **Chapter 2**.

The thickness of the housing has been modified to reduce noise on the sides. Comparing it with the existing housing produces the following figure.



#### To redefine contact:

Repeat the procedure in **Chapter 3** to redefine contact.

#### To save the model:

Save the model as VibratingTransmission\_RFlex\_NewHousing.rdyn.

#### To perform simulation after saving the model:

Execute the simulation in the same conditions as those simulated in **Chapter 4**.

### **Viewing the Acoustics Result**

6.00 

2.40

JU

0.00 LUUL & MIALL 1 SIA CONTROL 0000.0250.0000.0250.0000.0250.0000.0250.0500.0 0.00 250.0600.0750.0000.0250.0500.0750.0000.0250.0500.0 Frequency ٨

. 1.20

Repeat the Acoustics calculation procedure in Chapter 4 to calculate the ERP for the side of the housing again.





Cancel

ОК

Thanks for participating in this tutorial!

0.88 - Magnitude 0.66 0.44

> 0.22  $\mathcal{M}$

J  $\mathbf{\lambda}$ 

J

A

Cancel

ОК

å